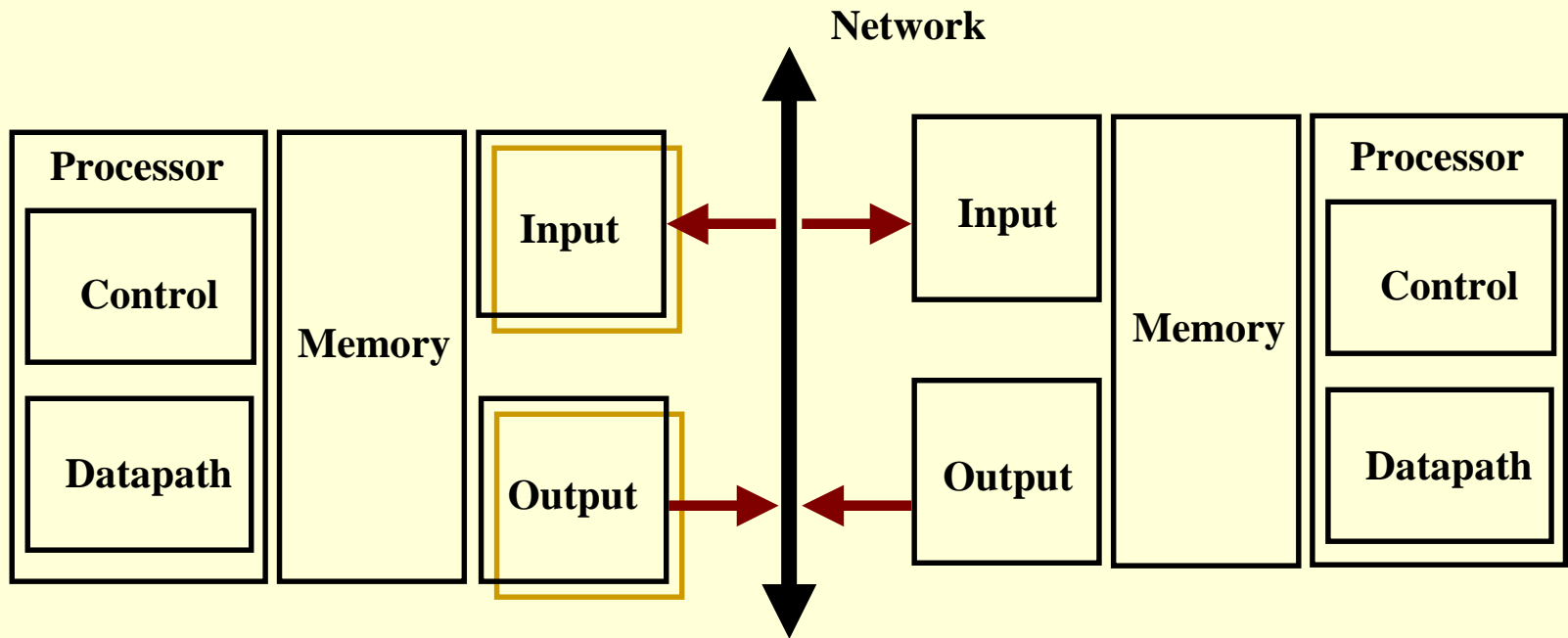


Input/Output



Exceptions and Interrupts

Terminology isn't consistent. We'll define:

- Exceptions: any unexpected change in control flow
Branches and jumps are not considered exceptions.
- Exceptions are classified as either:
 - Internal Interrupts: Exception caused by something in the execution pipeline.
 - arithmetic overflow
 - illegal instruction
 - divide by zero
 - user program invoking the OS
 - External Interrupts: ones caused by something else.
 - I/O device signals completion to CPU
 - memory parity error
 - timer signal
 - low battery warning

Handling exceptions

On an exception, the hardware needs to:

1. Save the PC (allows the OS look at the offending instructions and to later resume execution)
2. Record the nature of the exception/interrupt
3. Transfer control to exception handler (in OS)

Two ways to do 2 & 3:

- Write cause of exception in a status register; pass control to the exception handler.
- Use vectored interrupt: transfers control to a different location for each possible type of interrupt/exception

User versus System operation

- User-level programs are restricted.
 - Only program state instructions can be executed
 - No I/O, no ability to set the page table register, etc.
 - Memory references are virtual addresses to user's VM.
 - If a user program needs to do I/O, it signals the OS
 - Typically by raising an exception
- System programs run in supervisor (aka kernel) mode
 - Can execute privileged instructions for I/O, etc.
- To accomplish I/O, hardware needs ability for:
 - OS to tell I/O device what to do
 - I/O devices to notify OS (e.g. "I'm done" or "I failed")
 - Data to be transferred from device to memory

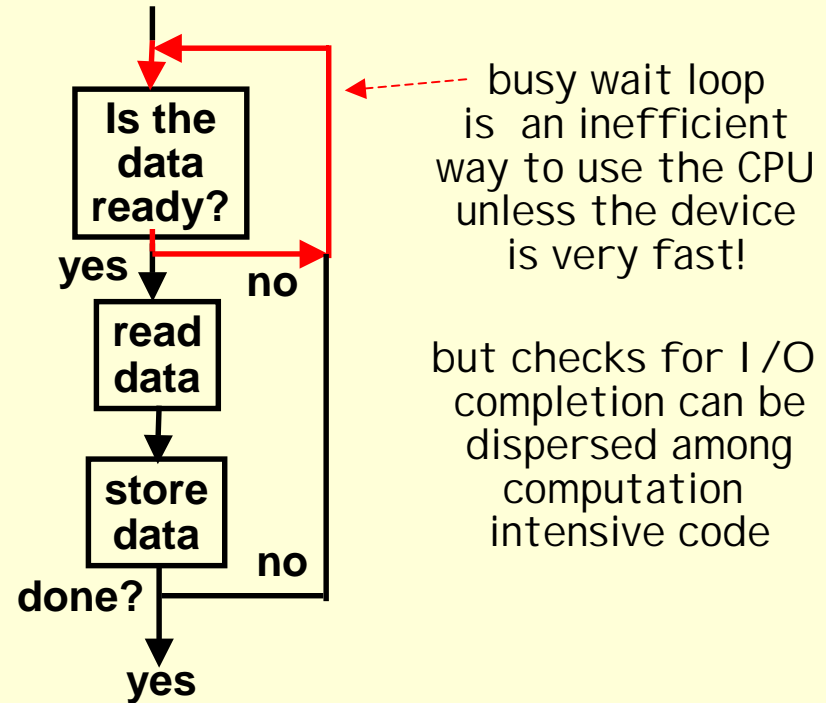
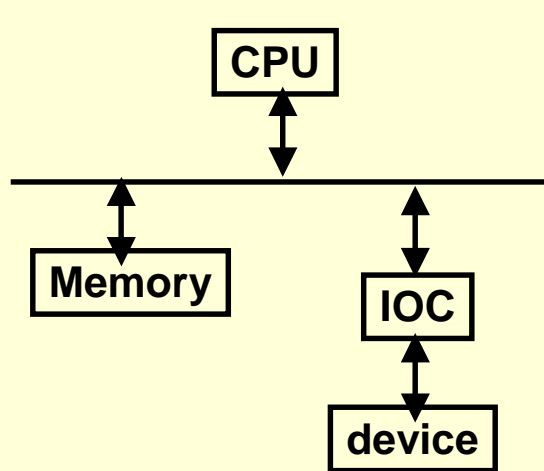
Giving Commands to I/O Devices

- Two methods are used to address I/O devices:
 - Special I/O instructions
 - Memory-mapped I/O
- Special I/O instructions specify a device number and a command
- Memory-mapped I/O:
 - Each I/O device is given a portion of the real address space
 - To prevent chaos, these addresses aren't mapped to users' virtual memory.
 - Read and writes to those addresses (by the OS) are interpreted as commands by the I/O device

I/O Device Notifying the OS

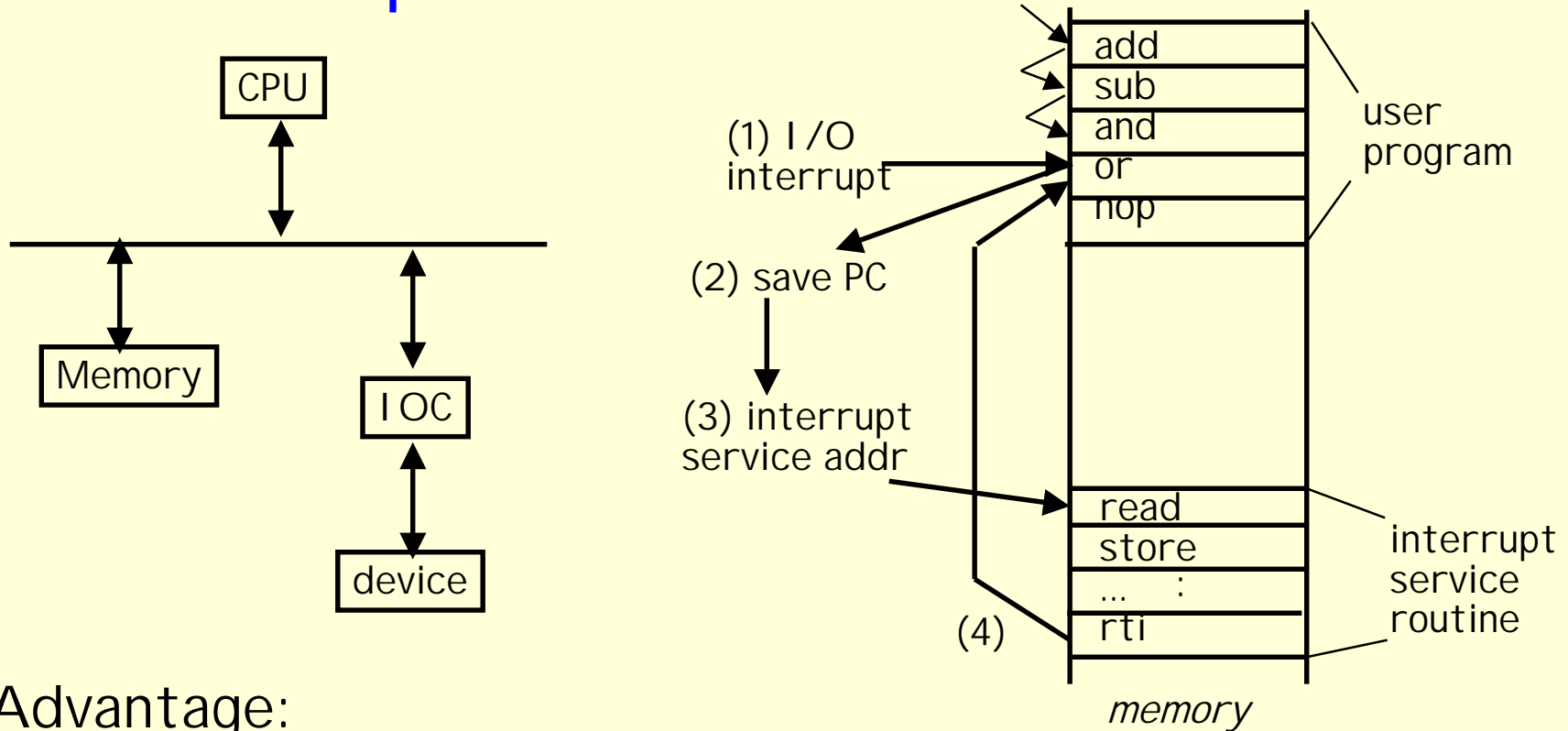
- The OS needs to know when:
 - The I/O device has completed an operation
 - The I/O operation has encountered an error
- This can be accomplished in two different ways:
 - Polling:
 - The I/O device put information in a status register
 - The OS periodically check the status register
 - I/O Interrupt:
 - Whenever an I/O device needs attention from the processor, it issues an interrupt to the processor.

Polling



- Advantage:
 - Simple: the processor is in control and does all the work
- Disadvantage:
 - Polling overhead can consume a lot of CPU time

Interrupt Driven Data Transfer



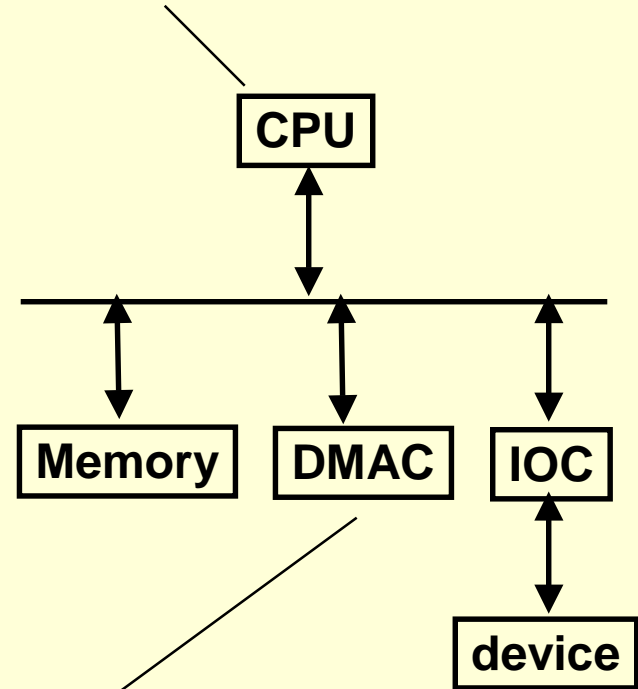
- Advantage:
 - User program is only halted during actual transfer
- Disadvantage:
 - Special hardware is needed to
 - Cause an interrupt (I/O device)
 - Detect an interrupt (processor)

Transferring Data to/from Memory

- Direct Memory Access (DMA):

- External to the CPU
- DMA controller is a bus master
- Transfer blocks of data to or from memory without CPU intervention

CPU sends a starting address, direction, and length count to DMA Controller.



DMA Controller does whatever is needed to get I O Controller and Memory to transfer data on the bus.

Network technologies

- Local Area Network (LAN)
 - Ethernet is most common LAN technology
 - 10 Mbit/sec, 100 Mbit/s ("fast Ethernet") and 1 Gbit/s ("Gigabit Ethernet") versions
 - Originally, used "Aloha" protocol
 - If line is quiet, sender dumps message on wire
 - If message got garbled with another message, all senders wait a random amount of time and retry
 - Limits throughput to about 70% peak
 - Today, often controlled by switches
- Wide Area Network (WAN)
 - IP (Internet Protocol) used on Internet.
 - TCP layer on top of IP resends lost packets, etc
 - ATM (Asynchronous Transfer Protocol)
 - Another protocol for long distances; 155 Mbit/sec to 2.5 Gbit/sec